## AMENDMENTS TO THE CLAIMS:

This listing of claims will replace all prior versions and listings of claims in the application:

1-24. (Cancelled)

25. (Currently Amended) An information providing apparatus for supplying motion data, stating the movements of a body unit of a robot apparatus, or an application program, managing recognition and/or action control, to a robot apparatus[[,]] over a network, i-said apparatus comprising:

content storage means having stered for storing data or programs to be supplied to the robot apparatus;

receiving means for receiving an inquiry, pertinent to <u>comprising</u> a service request and the information pertinent to <u>of</u> the robot apparatus[[,]] from the robot apparatus;

analyzing means for analyzing said inquiry;

preparing means for preparing a list of data or programs based on services requested in the service request and the information of the robot apparatus and for returning the list to the robot apparatus;

receiving means for receiving a selection of data or programs from the list from the robot apparatus; and

transmitting means for transmitting the selected data or programs,matched to services requested, to said the robot apparatus.

26. (Currently Amended) The information providing apparatus according to claim 25, wherein the <u>information providing</u> apparatus communicates with the robot apparatus in accordance with a <del>SOAP (</del>Simple Object Access Protocol [[])].

27. (Currently Amended) The information providing apparatus according to claim 25. further comprising:

a database for supervising the supplementary information pertinent to the data or programs stored in said the content storage means; and

means for taking the matching between-said the inquiry and the supplementary information of said-database, for preparing a list of data or programs that may be provided, and for returning said-list to the robot apparatus.

28. (Currently Amended) The information providing apparatus according to claim 27, further comprising:

means for returning, responsive to the results of in response to the selection from-said robot apparatus for said the list of the data or programs that ean be-provided, [[a]] an access method for accessing the selected data or programs selected to the robot apparatus, [[:]]

said wherein the transmitting means transmitting transmits the selected data or programs, as requested, responsive in response to an access request, matched to said corresponding to the accessing method, from said the robot apparatus.

- 29. (Currently Amended) The information providing apparatus according to claim 27, wherein said the supplementary information pertinent to said data or programs includes comprises the information pertinent to services and the information pertinent to information of the robot apparatus.
- 30. (Currently Amended) The information providing apparatus according to claim 25 or 29, wherein said the information pertinent to of the robot apparatus includes comprises at least a part of one the following information:
- (1) an ID proper to a of the robot apparatus, uniquely allocated wherein the ID is unique to each the robot apparatus;
- (2) a robot sort ID uniquely allocated, wherein the sort ID is unique to each of the sorts a type of the robot apparatus;
  - (3) a list of functions of the robot apparatus;
- (4) the information indicating the hardware architecture of the robot apparatus; and
  - (5) a database list owned by the robot apparatus.
- 31. (Currently Amended) An information providing apparatus for providing data or a program to a robot apparatus, over a network, said apparatus comprising:

content storage means having stored for storing data or programs to be supplied to the robot apparatus;

receiving means for receiving an inquiry, pertinent to comprising a service request and the information pertinent to the robot apparatus [[,]] from the robot apparatus;

analyzing means for analyzing said inquiry; and

preparing means for preparing a list of data or programs based on

services requested in the service request and the information of the robot

apparatus and for returning the list to the robot apparatus;

receiving means for receiving a selection of data or programs from the list from the robot apparatus,

transmitting-means-for-transmitting-data or-programs, matched to servicesrequested, to said-robot apparatus-said wherein the information-pertinent to of
the robot apparatus at-least-including comprises a list of functions of said the
robot apparatus, said apparatus further comprising;

means for specifying the <u>needed</u> functions needed for said <u>the</u> robot apparatus to render <u>the</u> services <u>requested</u>; and

means for comparing the needed functions specified by said functionspecifying means to said the list of functions of the robot apparatus for specifyingthe to determine functions in deficit in said the robot apparatus, among said the needed functions: means for retrieving one or more objects of functional objects

corresponding to the functions in deficit, from an object storage means for storing

functional objects utilized by the robot apparatus; and

said transmitting means for transmitting the objects and the selected data or programs for substituting the functions usable by said to the robot apparatus for said functions in deficit

32. (Currently Amended) The information providing apparatus according to claim 25, wherein the information pertinent to said of the robot apparatus includes at least comprises a list of functions of the robot apparatus, and said wherein the information providing apparatus further comprising

object storage means for storage of functional objects utilized by said the robot apparatus;

comprises:

means for specifying the <u>needed</u> functions <del>needed</del> for said <u>the</u> robot apparatus to render the services requested;

means for comparing the needed functions specified by said functionspecifying means to said the list of functions of the robot apparatus for specifyingthe to determine functions in deficit in said the robot apparatus[[,]] among said the needed functions; and

retrieving means for retrieving an object one or more objects of functional objects, matched to said corresponding to the function functions in deficit, from said the object storage means; said,

wherein the transmitting means transmitting said object of the function in deficit transmits the objects, along with the <u>selected</u> data or programs matched to the requested services, to said the robot apparatus.

33. (Currently Amended) An information providing method for supplying motion data, stating the movements of a body unit of a robot apparatus, or an application program, managing recognition and/or action control, to a robot apparatus, over a network, and the method comprising:

a receiving step of receiving, from said the robot apparatus [[,]] an inquiry containing the information pertinent to comprising a service request and the information pertinent to of said the robot apparatus;

an analysis stop of analyzing said inquiry;

formulating a list of data or programs that may be provided to the robot apparatus based on services requested in the service request and the information of the robot apparatus;

returning the list to the robot apparatus;

receiving a selection of data or programs from the list from the robot

## apparatus; and

a transmitting step of transmitting the <u>selected</u> data or <del>program programs,</del> matched to services requested, to said the robot apparatus.

34. (Currently Amended) The information providing method according to claim 33, wherein communication with the robot apparatus is by SOAP (Simple Object Access Protocol [[]]].

35. (Currently Amended) The information providing method according to claim 33, further comprising:

a step of supervising the supplementary information pertinent to each data or program as a database; and

a step of taking the matching of said the inquiry and the supplementary information of said database.

wherein the formulating [[a]] of the list of the data or programs that ean-beprovided is based on the matching of the inquiry and the supplementary
information—and

returning the list to the robot apparatus.

36. (Currently Amended) The information providing method according to claim 35, further comprising:

a step of returning, responsive to the results of in response to the selection from-said robot apparatus for said the list of the data or programs that ean-be-provided, [[a]] an access method for accessing the selected data or programs selected to the robot apparatus, [[:]]

said wherein transmitting-step the selected data comprises transmitting
the data or the program as requested, responsive to the in response to an

access request complying with said the access method from said the robot apparatus.

- 37. (Currently Amended) The information providing method according to claim 35, wherein said the supplementary information pertinent to said data or programs includes the comprises information pertinent to services and the information pertinent to information of the robot apparatus.
- 38. (Currently Amended) The information providing method according to claim 33 o<del>r 37</del>, wherein said the information pertinent to of the robot apparatus includes comprises at least a part of one the following information:
- (1) an ID proper to a of the robot apparatus, uniquely allocated wherein the ID is unique to each the robot apparatus;
- (2) a robot sort ID uniquely allocated, wherein the sort ID is unique to each of the sorts a type of the robot apparatus:
  - (3) a list of functions of the robot apparatus;
- (4) the information indicating the hardware architecture of the robot apparatus; and
  - (5) a database list owned by the robot apparatus.
- 39. (Currently Amended) An information providing method for providing data or a program to a robot apparatus, over a network, said <u>the</u> method comprising:

a receiving step of receiving, from said the robot apparatus, an inquiry containing the information pertinent to comprising a service request and the information pertinent to of said the robot apparatus;

an analysis step of analyzing said inquiry;

formulating a list of data or programs that may be provided to the robot apparatus based on services requested in the service request and the information of the robot apparatus;

returning the list to the robot apparatus;

receiving a selection of data or programs from the list from the robot

## apparatus; and

a transmitting step of transmitting the data or programs, matched toservices requested, to said robot apparatus;

said wherein the information pertinent to of the robot apparatus includingat least comprises a list of functions of the robot apparatus:[[,]]

said information providing method further comprising:

a step of specifying the <u>needed</u> functions needed for said <u>the</u> robot apparatus to render the services <u>requested</u>; and

a step of comparing the needed functions specified by said functionspecifying means to said the list of functions of the robot apparatus for specifyingthe to determine functions in deficit in said the robot apparatus, among said the
needed functions:

retrieving one or more objects of functional objects corresponding to the deficit functions, from an object storage means for storing functional objects utilized by the robot apparatus: and

said transmitting step transmitting the objects and the selected data or programs, for substituting the functions usable by said to the robot apparatus for the functions in deficit.

40. (Currently Amended) The information providing method according to claim 33, wherein the information pertinent to of said the robot apparatus includes at least comprises a list of functions of the robot apparatus, and said the information providing method further comprising:

a step of specifying the needed functions needed for said the robot

apparatus to render the services requested;

a step-of comparing the needed functions as specified by said neededfunction specifying step to said the list of functions of the robot apparatus for

specifying the  $\underline{to\ determine}$  functions in deficit in said  $\underline{the}$  robot apparatus, among

said the needed functions; and

a retrieving step of retrieving an object of the function in deficit one or more objects of functional objects corresponding, matched to said function the functions in deficit, from an object storage means having stored therein for storing functional objects utilized by said the robot apparatus; and

said transmitting step transmitting said object of the function in deficit the objects, along with the selected data or programs matched to the requested services, to said the robot apparatus.

41. (Currently Amended) An information providing system including comprising a robot apparatus and an information providing apparatus for supplying motion data, stating the movements of a body unit of said the robot apparatus, or an application program, managing recognition and/or action control, to [[a]] the robot apparatus[[,]] over a network[[,]], said wherein the information providing apparatus comprises comprising:

content storage means having stered for storing data or programs to be supplied to the robot apparatus;

receiving means for receiving an inquiry, pertinent to comprising a service request and the information pertinent to of the robot apparatus, from the robot apparatus;

analyzing means for analyzing said inquiry;

means for preparing a list of data or programs based on services

requested in the service request and the information of the robot apparatus and

for returning the list to the robot apparatus:

means for receiving a selection of data or programs from the list from the robot apparatus; and

transmitting means for transmitting the selected data or programs,matched to services requested, to said the robot apparatus.

- 42. (Currently Amended) The information providing method system according to claim 41, wherein the method information providing apparatus communicates with the robot apparatus in accordance with a SOAP (Simple Object Access Protocol [[)]].
- 43. (Currently Amended) The information providing method system according to claim 41, wherein the information providing apparatus further comprising comprises:

a database for supervising [[the]] supplementary information pertinent to the data or programs stored in said the content storage means; and

means of taking the for matching between said the inquiry and the supplementary information of said database, for preparing a list of data or programs that may be provided, and for returning said list to the robot apparatus.

44. (Currently Amended) The information providing system according to claim 41, wherein the information providing apparatus further comprising comprises:

means for returning, responsive to the results of in response to the selection from said robot apparatus for said the list of the data or programs that can be provided, [[a]] an access method for accessing the selected data or programs selected to the robot apparatus:

said wherein the transmitting means transmitting transmits the selected data or programs, as requested, responsive in response to an access request, matched to said corresponding to the accessing method, from said the robot apparatus.

- 45. (Currently Amended) The information providing method system according to claim 43, wherein said the supplementary information pertinent to said data or programs includes comprises the information pertinent to services and information pertinent to information of the robot apparatus.
- 46. (Currently Amended) The information providing system according to claim 41 er 45, wherein said the information pertinent to of the robot apparatus includes comprises at least a part of one the following information:
- (1) an ID proper-to-a of the robot apparatus, uniquely-allocated wherein the ID is unique to each the robot apparatus:
- (2) a robot sort ID uniquely allocated, wherein the sort ID is unique to each of the sorts a type of the robot apparatus;
  - (3) a list of functions of the robot apparatus;
- (4) the information indicating the hardware architecture of the robot apparatus; and
  - (5) a database list owned by the robot apparatus.

47. (Currently Amended) The information providing system according to claim 41, wherein said the information pertinent to of the robot apparatus includes at least comprises a list of functions of the robot apparatus, and said wherein the information providing apparatus further comprising comprises:

means for specifying the <u>needed</u> functions <del>needed</del> for said the robot apparatus to render the services requested; and

means for comparing the needed functions specified by said functionspecifying means to said the list of functions of the robot apparatus for specifyingthe to determine functions in deficit in said the robot apparatus, among said the needed functions; and

means for retrieving one or more objects of functional objects

corresponding to the deficit functions, from an object storage means for storing

functional objects utilized by the robot apparatus,

said wherein the transmitting means transmitting transmits the objects and the selected data or programs for substituting the functions usable by said to the robot apparatus for said functions in deficit.

48. (Currently Amended) The information providing system according to claim 41, wherein the information pertinent to of said the robot apparatus includes at least comprises a list of functions of the robot apparatus, and said wherein the information providing apparatus further comprising comprises:

object storage means having stored therein the for storing functional objects utilized by eaid the robot apparatus;

means for specifying [[the]] <u>needed</u> functions <del>needed</del> for said <u>the</u> robot apparatus to render services:

means for comparing the needed functions specified by said functionspecifying means to said the list of functions of the robot apparatus for specifyingthe to determine functions in deficit in said the robot apparatus, among said the needed functions; and

retrieving means for retrieving an object of the function in deficit one or more objects of the functional objects corresponding, matched to said function the functions in deficit, from said the object storage means;

said wherein the transmitting means transmitting transmits said object of the function in deficit the objects, along with the selected data or programs matched to the requested services, to said the robot apparatus.